

# CURRICULUM VITAE

## **Andrea Garulli**

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## **Personal Data and Education**

- Birthdate : June 17, 1968.
- Birthplace : Bologna (Italy).
- Laurea Degree in *Electronic Engineering* (cum laude) from Università di Firenze, in 1993.
- Ph.D. in *System Engineering* from Università di Bologna, in 1997.
- August 1994: NATO ASI school "From Identification to Learning", Como (Italy).
- March-April 1996: visiting scientist at the Department of Mechanical and Environmental Engineering of the University of California at Santa Barbara.
- September 1999: visiting scientist at the Department of Electrical Engineering of the University of Linköping, Svezia.

## **Academic positions**

- 1996-2001: Assistant Professor in Control Systems, Dipartimento di Ingegneria dell'Informazione, Università di Siena.
- 2001-2006: Associate Professor in Control Systems, Dipartimento di Ingegneria dell'Informazione, Università di Siena.
- 2006-present: Professor in Control Systems, Dipartimento di Ingegneria dell'Informazione e Scienze Matematiche, Università di Siena.
- 2011-2012: Dean of the Faculty of Engineering, Università di Siena.
- 2015-present: Director of the Dipartimento di Ingegneria dell'Informazione e Scienze Matematiche, Università di Siena.

## Teaching

- 1999-present: Courses on Dynamic Systems, Modelling and Identification, at the Faculty of Engineering, Università di Siena.
- 2002-2012: Course on Linear Systems at the Faculty of Engineering, Università di Siena (in Arezzo).
- 2002: Course on Statistics for the Master E2C, Università di Siena.
- 1996-99: Teaching assistant at the Faculty of Engineering, Università di Siena, for courses on System Theory, Control Systems, System Modelling and Identification.
- 1995: Lectures on Control Systems at the PIN Institute, Prato (Italy).

## Organizing and Editorial Activities

- 2002-2005: Associate Editor of *IEEE Transactions on Automatic Control*.
- 2006-2010: Associate Editor of *Journal of Control Science and Engineering*.
- 2000-2003: Member of the Conference Editorial Board of the *IEEE Control Systems Society*. Associate editor for the IEEE Conference on Decision and Control and American Control Conference.
- Program Committee Member of:
  - IEEE Joint Symposium on Computer-Aided Control System Design and Systems with Uncertainty (Hyderabad, India, 2013)
  - IFAC Joint conference on System Structure and Control, Time-Delay Systems, Fractional Differentiation and Its Applications (Grenoble, France, 2013)
  - 7th IFAC Symposium on Robust Control Design (Aalborg, Denmark, 2012)
  - 16th IFAC Symposium on System Identification (Brussels, 2012)
  - 2011 IEEE International Conference on Intelligent Robotics, Automations and Applications (Gwangju, Korea, 2011)
  - 2011 IEEE Multi-Conference on Systems and Control (Denver, 2011)
  - 7th International Conference on Informatics in Control, Automation and Robotics (Funchal, 2010)

- 2010 IEEE International Symposium on Computer-Aided Control System Design (Yokohama, 2010)
  - 15th IFAC Symposium on System Identification (Saint-Malo, 2009)
  - 6th International Conference on Informatics in Control, Automation and Robotics (Milan, 2009)
  - 5th IFAC Symposium on Robust Control Design (Toulouse, 2006);
  - 2005 American Control Conference (Portland, 2005);
  - 43rd IEEE Conference on Decision and Control (Bahamas, 2004).
- Co-organizer of the invited sessions
    - “Piecewise affine models and quantized information”, 16th IFAC Symposium on System Identification, Brussels (Belgium), 2012.
    - “Current trends in identification of switched and piecewise affine systems”, 15th IFAC Symposium on System Identification, Saint-Malo (France), 2009.
    - “Positive polynomials and LMI optimization with applications to robust control”, 16th IFAC World Congress, Prague, 2005.
    - “Positive Polynomials in Control”, 42nd IEEE Conference on Decision and Control, Maui (USA), 2003.
- Guest Editor of the Special Issue “Robustness in Identification and Control”, *International Journal of Robust and Nonlinear Control*, vol. 11, no. 7, June 2001.
- Outstanding reviewer for *Automatica* in 1999.
- Co-organizer of the International Workshop on *Robustness in Identification and Control*, held in Siena, July 30 - August 2, 1998.
- Senior Member of the IEEE.

## Research Projects

### Principal Investigator

- European Commission (6th FP): “Clearance of flight control laws using optimization (COFCLUO)”, 2007-2010.
- National Government (Ministry of Research): “Localization, map building and motion planning algorithms for teams of heterogeneous autonomous vehicles ”, 2006-2007.
- University of Siena: “Techniques and algorithms for autonomous navigation of a team of mobile robots”, 2006-2007.
- National Government (Ministry of Research): “Identification and filtering algorithms with guaranteed uncertainty for unmanned aerial vehicles”, 2003-2004.
- National Government (Ministry of Research): “Self-localization algorithms for air and marine vehicles with guaranteed uncertainty bounds”, 2001-2002.
- National Research Council - Young Researchers: “Simultaneous map building and localization of mobile robots in unstructured environments: techniques and algorithms”, 2000.

### Partecipation

- UE Project ACANTO: “A cyberphysical social network using robot friends”, H2020, 2015-2018.
- UE Project DALi: “Devices for Assisted Living”, FP7, 2011-2014.
- UE Project ADDRESS: “Active distribution network with full integration of demand and distributed energy resources”, 2010-2013.
- UE Project: “Development of an information technology tool for the management of european southern lagoons under the influence of river-basin runoff - DITTY Project”, Specific Programme: Energy, Environment and Sustainable Development, 2003-2005.
- National Government (Ministry of Research): “Techniques and algorithms for identification and robust control of dynamic systems”, 2003-2004.
- University of Siena: “Techniques and algorithms for optimization and robust control of systems with structured uncertainties”, 2003-2004.

- ASI (Italian Space Agency): “TEMA - Team-based exploration by mobile agents”, 2000-2002.
- National Government (Ministry of Research): “The use of satellite-based techniques for air and maritime navigation and traffic control in constrained areas”, 2000.
- ASI (Italian Space Agency): “Team-based Exploration by Mobile Agents”, 1999-2000.
- ASI (Italian Space Agency): “Dynamic Models and Estimation Techniques for Constructing and Updating Navigation Maps for Mobile Robots”, 1997-1998.
- INTAS (CEE), Project INTAS-93-1034: “Robust control with nonlinear dependence on uncertain parameters”, in cooperation with DLR-Munich (Germany), University of St. Petersburg (Russia), Accademy of Sciences of Moscow (Russia), 1996-1997.
- National Research Council: “Algorithms for Identification and Robust Control of Uncertain Systems”, 1996-1997.
- National Government (Ministry of Research): “ Robust Identification and Control of Uncertain Systems”, 1993-1996.

# Publications of Andrea Garulli

## Books and Special Issues

- [L1] A. Garulli, A. Tesi and A. Vicino (Editors), *Robustness in Identification and Control*, Lecture Notes in Control and Information Sciences, no. 245, Springer-Verlag, 1999.
- [L2] A. Garulli and A. Vicino (Guest Editors), Special Issue “Robustness in Identification and Control”, su *International Journal of Robust and Nonlinear Control*, vol. 11, no. 7, June 2001.
- [L3] D. Henrion and A. Garulli (Editors), *Positive Polynomials in Control*, Lecture Notes in Control and Information Sciences, no. 312, Springer-Verlag, 2005.
- [L4] G. Chesi, A. Garulli, A. Tesi and A. Vicino, *Homogeneous Polynomials Forms for Robustness Analysis of Uncertain Systems*, Lecture Notes in Control and Information Sciences, no. 390, Springer-Verlag, 2009.

## Journal papers

- [J1] L. Chisci, A. Garulli and G. Zappa, “Fast algorithms for generalized predictive control”, *System and Control Letters*, vol. 23, pp. 339-348, 1994.
- [J2] L. Chisci, A. Garulli and G. Zappa, “Recursive state bounding by parallelotopes”, *Automatica*, vol. 32, pp. 1049-1056, 1996.
- [J3] L. Chisci, A. Garulli and G. Zappa, “Fast parallel LQ regulator design for adaptive control”, *Int. J. of Adaptive Control and Signal Processing*, vol. 11, pp. 395-413, 1997.
- [J4] L. Chisci, A. Garulli, A. Vicino and G. Zappa, “Block recursive parallelotopic bounding in set membership identification”, *Automatica*, vol. 34, pp. 15-22, 1998.
- [J5] A. Garulli, B. Z. Kacewicz, A. Vicino and G. Zappa, “Reliability of projection algorithms in conditional estimation”, *Journal of Optimization Theory and Applications*, vol. 101, no. 1, pp. 1-14, 1999.

- [J6] A. Garulli, A. Vicino and G. Zappa, "Optimal induced-norm and set membership state smoothing and filtering for linear systems with bounded disturbances", *Automatica*, vol. 35, no. 5, pp. 767-776, 1999.
- [J7] A. Garulli, "Tight error bounds for projection algorithms in conditional set membership estimation", *Systems and Control Letters*, vol. 37, no. 5, pp. 293-300, 1999.
- [J8] A. Garulli, A. Vicino and G. Zappa, "Conditional central algorithms for worst-case set membership identification and filtering", *IEEE Transactions on Automatic Control*, vol. 45, no. 1, pp. 14-23, 2000.
- [J9] A. Garulli, B. Z. Kacewicz, A. Vicino and G. Zappa, "Error bounds for conditional algorithms in restricted complexity set membership identification", *IEEE Transactions on Automatic Control*, vol. 45, no. 1, pp. 160-164, 2000.
- [J10] A. Bemporad and A. Garulli, "Output-feedback predictive control of constrained linear systems via set-membership state estimation", *International Journal of Control*, vol. 73, no. 8, pp. 655-665, 2000.
- [J11] A. Garulli, "Robust control: the parametric approach, by S. P. Bhattacharyya, H. Chapellat and L. H. Keel" (Book review), *Automatica*, vol. 36, no. 10, pp. 1563-1566, 2000.
- [J12] A. Garulli and A. Vicino, "Set membership localization of mobile robots via angle measurements", *IEEE Transactions on Robotics and Automation*, vol. 17, no. 4, pp. 450-463, 2001.
- [J13] M. Di Marco, A. Garulli, S. Lacroix and A. Vicino, "Set membership localization and mapping for autonomous navigation", *International Journal of Robust and Nonlinear Control*, vol. 11, no. 7, pp. 709-734, 2001.
- [J14] G. Chesi, A. Garulli, A. Tesi and A. Vicino, "A convex approach to the characterization of the frequency response of ellipsoidal plants", *Automatica*, vol. 38, no. 2, pp. 249-259, 2002.
- [J15] G. Chesi, A. Garulli, A. Vicino and R. Cipolla, "Estimating the fundamental matrix via constrained least squares: a convex approach", *IEEE Transactions on Pattern Analysis and Machine Intelligence*, vol. 24, no. 3, pp. 397-401, 2002.
- [J16] W. Reinelt, A. Garulli and L. Ljung, "Comparing different approaches to model error modeling in robust identification", *Automatica*, vol. 38, no. 5, pp. 787-803, 2002.

- [J17] A. Caiti, A. Garulli, F. Livide and D. Prattichizzo “Set-membership acoustic tracking of autonomous underwater vehicles”, *Acta Acustica united with Acustica*, vol. 88, no. 5, pp. 648-652, 2002.
- [J18] A. Garulli, L. Giarrè and G. Zappa, “Identification of approximated Hammerstein models in a worst-case setting”, *IEEE Transactions on Automatic Control*, vol. 47, no. 12, pp. 2046-2050, 2002.
- [J19] M. Casini, A. Garulli and A. Vicino, “On worst-case approximation of feasible system sets via orthonormal basis functions”, *IEEE Transactions on Automatic Control*, vol. 48, no. 1, pp. 96-101, 2003.
- [J20] G. Chesi, A. Garulli, A. Tesi and A. Vicino, “Solving quadratic distance problems: an LMI-based approach”, *IEEE Transactions on Automatic Control*, vol. 48, no. 2, pp. 200-212, 2003.
- [J21] A. Garulli, C. Mocenni, A. Tesi and A. Vicino, “Integrating identification and qualitative analysis for the dynamic model of a lagoon”, *International Journal of Bifurcation and Chaos*, vol. 13, no. 2, pp. 357-374, 2003.
- [J22] M. Di Marco, A. Garulli, A. Giannitrapani and A. Vicino, “Simultaneous localization and map building for a team of cooperating robots: a set membership approach”, *IEEE Transactions on Robotics and Automation*, vol. 19, no. 2, pp. 238-249, 2003.
- [J23] G. Chesi, A. Garulli, A. Tesi and A. Vicino, “Homogeneous Lyapunov functions for systems with structured uncertainties”, *Automatica*, vol. 39, no. 6, pp. 1027-1035, 2003.
- [J24] M. Di Marco, A. Garulli, D. Prattichizzo and A. Vicino, “A set theoretic approach for time-to-contact estimation in dynamic vision”, *Automatica*, vol. 39, no. 6, pp. 1037-1044, 2003.
- [J25] G. Chesi, A. Garulli, A. Tesi and A. Vicino, “Characterizing the solution set of polynomial systems in terms of homogeneous forms: an LMI approach”, *International Journal of Robust and Nonlinear Control*, vol. 13, no. 13, pp. 1239–1257, 2003.
- [J26] M. Di Marco, A. Garulli, A. Giannitrapani and A. Vicino, “A set theoretic approach to dynamic robot localization and mapping”, in *Autonomous Robots*, vol. 16, pp. 23-47, 2004.
- [J27] G. Chesi, A. Garulli, A. Tesi and A. Vicino, “Robust analysis of LFR systems through homogeneous polynomial Lyapunov functions”, *IEEE Transactions on Automatic Control*, vol. 49, no. 7, pp. 1211-1216, 2004.



- [J28] G. Chesi, A. Garulli, A. Tesi, and A. Vicino “LMI-based computation of optimal quadratic Lyapunov functions for odd polynomial systems”, *International Journal of Robust and Nonlinear Control*, vol. 15, pp. 34–49, 2005.
- [J29] G. Chesi, A. Garulli, A. Tesi, and A. Vicino “Polynomially parameter-dependent Lyapunov functions for robust stability of polytopic systems: an LMI approach”, *IEEE Transactions on Automatic Control*, vol. 50, no. 3, pp. 365–370, 2005.
- [J30] A. Caiti, A. Garulli, F. Livide and D. Prattichizzo, “Localization of autonomous underwater vehicles by floating acoustic buoys: a set-membership approach”, *IEEE Journal of Oceanic Engineering*, vol. 30, no. 1, pp. 140-152, 2005.
- [J31] M. Casini, A. Garulli, D. Prattichizzo and A. Vicino, “Remote identification and control experiments on a DC motor”, *Learning Technology*, vol. 7, no. 3, pp. 36-39, 2005.
- [J32] A. Bemporad, A. Garulli, S. Paoletti and A. Vicino, “A bounded-error approach to piecewise affine system identification”, *IEEE Transactions on Automatic Control*, vol. 50, no. 10, pp. 1567-1580, 2005.
- [J33] M. Casini, A. Garulli and A. Vicino, “On input design in  $\ell_\infty$  conditional set membership identification”, *Automatica*, vol. 42, no. 5, pp. 815-823, 2006.
- [J34] G. Chesi, A. Garulli, A. Tesi, and A. Vicino “Robust stability of time-varying polytopic systems via parameter-dependent homogeneous Lyapunov functions”, *Automatica*, vol. 43, no. 2, pp. 309-316, 2007.
- [J35] F. Morbidi, A. Garulli, D. Prattichizzo, C. Rizzo, P. Manganotti and S. Rossi, “Off-line removal of TMS-induced artifacts on human electroencephalography by Kalman filter”, *Journal of Neuroscience Methods*, vol. 162, no. 1-2, pp. 293-302, 2007.
- [J36] M. Casini, A. Garulli and A. Vicino, “Efficient computation of  $\ell_1$  uncertainty model from an impulse response set”, *Automatica*, vol. 44, no. 10, pp. 2570-2576, 2008.
- [J37] F. Morbidi, A. Garulli, D. Prattichizzo, C. Rizzo and S. Rossi, “Application of Kalman filter to remove TMS-induced artifacts from EEG recordings”, *IEEE Transactions on Control Systems Technology*, vol. 16, no. 6, pp. 1360-1366, 2008.
- [J38] N. Ceccarelli, M. Di Marco, A. Garulli and A. Giannitrapani, “Collective circular motion of multi-vehicle systems”, *Automatica*, vol. 44, no. 12, pp. 3025-3035, 2008.

- [J39] A. Garulli and A. Vicino, “Convex relaxations in circuits, systems, and control”, *IEEE Circuits and Systems Magazine*, vol. 9, no. 2, pp. 46-56, 2009.
- [J40] S. Paoletti, J. Roll, A. Garulli and A. Vicino, “On the input-output representation of piecewise affine state space models”, *IEEE Transactions on Automatic Control*, vol. 55, no. 1, pp. 60-73, 2010.
- [J41] D. Benedettelli, N. Ceccarelli, A. Garulli and A. Giannitrapani, “Experimental validation of collective circular motion for nonholonomic multi-vehicle systems”, *Robotics and Autonomous Systems*, vol. 58, no. 8, pp. 1028-1036, 2010.
- [J42] A. Garulli, A. Giannitrapani “Analysis of consensus protocols with bounded measurement errors”, *Systems and Control Letters*, vol. 60, no. 1, pp. 44-52, 2011.
- [J43] E. Pepona, S. Paoletti, A. Garulli and P. Date, “Identification of piecewise affine LFR models of interconnected systems”, *IEEE Transactions on Control Systems Technology*, vol. 19, no. 1, pp. 148-155, 2011.
- [J44] A. Giannitrapani, N. Ceccarelli, F. Scortecci and A. Garulli, “Comparison of EKF and UKF for spacecraft localization via angle measurements”, *IEEE Transactions on Aerospace and Electronic Systems*, vol. 74, no. 1, pp. 75-84, 2011.
- [J45] N. Ceccarelli, M. Di Marco, A. Garulli, A. Giannitrapani and A. Vicino, “Path planning with uncertainty: a set membership approach”, *International Journal on Adaptive Control and Signal Processing*, vol. 25, pp. 273-287, 2011.
- [J46] M. Casini, A. Garulli and A. Vicino, “Input design in worst-case system identification using binary sensors”, *IEEE Transactions on Automatic Control*, vol. 56, no. 5, pp. 1186-1191, 2011.
- [J47] A. Garulli, A. Giannitrapani, M. Leomanni and, F. Scortecci, “Autonomous low-Earth-orbit station-keeping with electric propulsion”, *Journal of Guidance Control and Dynamics*, vol. 34, no. 6, pp. 1683-1693, 2011.
- [J48] A. Fabbrini, A. Garulli and P. Mercorelli, “A trajectory generation algorithm for optimal consumption in electromagnetic actuators ”, *IEEE Transactions on Control Systems Technology*, vol. 20, no. 4, pp. 1025-1032, 2012.
- [J49] D. Benedettelli, A. Garulli and A. Giannitrapani, “Cooperative SLAM using M-Space representation of linear features”, *Robotics and Autonomous Systems*, vol. 60, no. 10, pp. 1267-1278, 2012.

- [J50] M. Casini, A. Garulli and A. Vicino, “Input design in worst-case system identification with quantized measurements”, *Automatica*, vol. 48, no. 12, pp. 2997-3007, 2012.
- [J51] A. Garulli, A. Masi, G. Valmorbida and L. Zaccarian, “Global stability and finite  $\mathcal{L}_{2m}$ -gain of saturated uncertain systems via piecewise polynomial Lyapunov functions”, *IEEE Transactions on Automatic Control*, vol. 58, no. 1, pp. 242-246, 2013.
- [J52] A. Garulli, A. Hansson, S. Khoshfetrat Pakazad, A. Masi, R. Wallin, “Robust finite-frequency  $\mathcal{H}_2$  analysis of uncertain systems with application to flight comfort analysis”, *Control Engineering Practice*, vol. 21, no. 6, pp. 887-897, 2013.
- [J53] A. Garulli, A. Masi, and A. Vicino, “Equivalence of sum of squares convex relaxations for quadratic distance problems”, *International Journal of Robust and Nonlinear Control*, vol. 23, no. 9, pp. 965-977, 2013.
- [J54] M. Casini, A. Garulli, A. Giannitrapani and A. Vicino, “A remote lab for experiments with a team of mobile robots”, *Sensors*, vol. 14, no. 9, pp. 16486-16507, 2014.
- [J55] F. Taccogna, D. Pagano, F. Scortecci and A. Garulli, “Three-dimensional plume simulation of multi-channel thruster configuration”, *Plasma Sources Science and Technology*, vol. 23, no. 6, pp. 065034, 2014.
- [J56] M. Casini, A. Garulli and A. Vicino, “Feasible parameter set approximation for linear models with bounded uncertain regressors”, *IEEE Transactions on Automatic Control*, vol. 59, no. 11, pp. 2910-2920, 2014.
- [J57] M. Leomanni, A. Garulli, A. Giannitrapani and, F. Scortecci, “All-electric spacecraft precision pointing using model predictive control”, *Journal of Guidance Control and Dynamics*, vol. 38, no. 1, pp. 161-167, 2015.
- [J58] L. Palopoli, A. Argyros, J. Birchbauer, A. Colombo, D. Fontanelli, A. Legay, A. Garulli, A. Giannitrapani, et al., “Navigation assistance and guidance of older adults across complex public spaces: the DALi approach”, *Intelligent Service Robotics*, pp. 1-16, 2015.
- [J59] A. Garulli, S. Paoletti and A. Vicino, “Models and techniques for electric load forecasting in the presence of demand response”, *IEEE Transactions on Control Systems Technology*, vol. 23, no. 3, pp. 1087-1097, 2015.
- [J60] A. Garulli, A. Giannitrapani and M. Leomanni, “Minimum switching control for systems of coupled double integrators”, *Automatica*, vol. 60, pp. 115-121, 2015.

## Book chapters

- [B1] A. Garulli, B. Z. Kacewicz, A. Vicino and G. Zappa, “Suboptimal conditional estimators for restricted complexity set membership identification”, in *Robustness in Identification and Control* (A. Garulli, A. Tesi and A. Vicino eds.), Lecture Notes in Control and Information Sciences, no. 245, pp. 117-133, Springer Verlag, 1999.
- [B2] G. Chesi, A. Garulli, A. Tesi and A. Vicino, “On the role of homogeneous forms in robustness analysis of control systems”, in *Multidisciplinary Research in Control: The Mohammed Dahleh Symposium 2002* (L. Giarre’ and B. Bamieh Eds.), Lecture Notes in Control and Information Sciences, no. 289, pp. 161-177, Springer-Verlag, Berlin, 2003.
- [B3] A. Bemporad, A. Garulli, S. Paoletti and A. Vicino, ”A greedy approach to identification of piecewise affine models”, in *Hybrid Systems: Computation and Control* (O. Maler and A. Pnueli Eds.), Lecture Notes in Computer Science, no. 2623, pp. 97-112, Springer-Verlag, 2003.
- [B4] A. Garulli, A. Tesi and A. Vicino, “Uncertainty models for robustness analysis”, in *Control Systems, Robotics and Automation*, edited by H. Unbehauen, in Encyclopedia of Life Support Systems (EOLSS), developed under the auspices of the UNESCO, Eolss Publishers, Oxford, UK, 2004. [<http://www.eolss.net>]
- [B5] G. Chesi, A. Garulli, A. Tesi and A. Vicino, “An LMI-based technique for robust stability analysis of linear systems with polynomial parametric uncertainties”, in *Positive polynomials in control* (A. Garulli and D. Henrion Eds.), Lecture Notes on Control and Information Sciences, vol. 312, Springer-Verlag, Berlin, 2005.
- [B6] N. Ceccarelli, M. Di Marco, A. Garulli, A. Giannitrapani and A. Vicino, “Set membership localization and map building for mobile robots”, in *Current Trends in Nonlinear Systems and Control* (L. Menini, L. Zaccarian and C.T. Abdallah Eds.), pp. 289-308, Birkhauser, 2006.
- [B7] A. Garulli, A. Masi, S. Paoletti and E. Turkoglu, “Lyapunov-based robustness analysis techniques for clearance”, in *Optimization Based Clearance of Flight Control Laws: A Civil Aircraft Application* (A. Varga, A. Hansson and G. Puyou Eds.), pp. 161-178, Lecture Notes in Control and Information Sciences, vol. 416, pp. 161-178, Springer, 2012.

- [B8] A. Garulli, A. Masi, S. Paoletti and E. Turkoglu, “Applications of Lyapunov-based analysis techniques for clearance”, in *Optimization Based Clearance of Flight Control Laws: A Civil Aircraft Application* (A. Varga, A. Hansson and G. Puyou Eds.), pp. 253-275, Lecture Notes in Control and Information Sciences, vol. 416, pp. 253-275, Springer, 2012.
- [B9] R. Wallin, S. Khoshfetrat Pakazad, A. Hansson, A. Garulli and A. Masi, “Applications of IQC-Based analysis techniques for clearance”, in *Optimization Based Clearance of Flight Control Laws: A Civil Aircraft Application* (A. Varga, A. Hansson and G. Puyou Eds.), pp. 277-297, Lecture Notes in Control and Information Sciences, vol. 416, pp. 277-297, Springer, 2012.
- [B10] S. Paoletti and A. Garulli, “PWA identification of interconnected systems with LFR structure”, in *Linear Parameter-Varying System Identification - New Developments and Trends*, (P. Lopes dos Santos, T. P. Azevedo Perdicoulis, C. Novara, J. A. Ramos and D. E. Rivera Eds.), pp. 317-346, Advanced Series in Electrical and Computer Engineering, vol. 14, World Scientific, 2012.

## Conference papers

- [C1] L. Chisci, A. Garulli and G. Zappa, “Fast algorithms for LQ control design of time-invariant systems”, *Proc. of the 32th IEEE CDC*, San Antonio, pp. 116-121, 1993.
- [C2] L. Chisci, A. Garulli and G. Zappa, “From systolic to transputer arrays: a clustering approach”, *Proc. of the 4th Symposium on Automatic Control and Computer Science*, Iasi, Romania, pp. 430-441, 1993.
- [C3] L. Chisci, A. Garulli and G. Zappa, “Recursive set membership state estimation via parallelotopes”, *Prep. 9th IFAC/IFORS SYSID*, vol. III, Copenhagen, pp. 383-388, 1994.
- [C4] L. Chisci, A. Garulli and G. Zappa, “Fast parallel algorithms for predictive control”, *Proc. of Control '94*, Warwick, pp. 1248-1253, 1994.
- [C5] L. Chisci, A. Garulli and G. Zappa, “Fast computation of stabilizing predictive control laws”, *Prep. 3rd IFAC/IFIP Workshop on Algorithms and Architectures for Real-Time Control*, Ostend, pp. 525-531, 1995.
- [C6] L. Chisci, A. Garulli and G. Zappa, “Properties of optimal bounding parallelotope algorithms”, *Proc. of the 3rd ECC*, Roma, pp. 7-12, 1995.

- [C7] L. Chisci, A. Garulli, A. Vicino and G. Zappa, "Block recursive bounding in set membership identification", *Proc. of the 34th IEEE CDC*, New Orleans, pp. 3516-3521, 1995.
- [C8] L. Chisci, A. Garulli, A. Vicino and G. Zappa, "Recursive parallelotopic bounding algorithms in set membership identification", *Proc. of the 13th IFAC World Congress*, San Francisco, vol. I, pp. 49-54, 30 Giugno-5 Luglio 1996.
- [C9] A. H. Sayed, A. Garulli and S. Chandrasekaran "Iterative solution of min-max parameter estimation with bounded uncertainties", *Proc. ICASSP'97*, Munich, Germany, pp. 3561-3564, 21-24 Aprile 1997.
- [C10] A. H. Sayed, A. Garulli and S. Chandrasekaran, "A fast iterative solution for worst-case parameter estimation with bounded model uncertainties", *Proc. ACC'97*, Albuquerque, New Mexico, pp. 1499-1503, vol. 3, 4-6 Giugno 1997.
- [C11] A. H. Sayed, A. Garulli, V. H. Nascimento and S. Chandrasekaran, "Exponentially-weighted iterative solutions for worst-case parameter estimation", *Proc. 5th Mediterranean Conf. on Control and Systems*, Cyprus, 21-23 Luglio 1997.
- [C12] A. Garulli, P. Guarnieri, A. Vicino and G. Zappa, "Set membership identification of mixed parametric/nonparametric models for robust control", *Prep. of the 2nd IFAC Symposium on Robust Control Design*, Budapest, pp. 95-100, 25-27 Giugno 1997.
- [C13] A. Bemporad and A. Garulli, "Predictive control via set-membership state estimation for constrained linear systems with disturbances", *Proc. of the 4th ECC*, Bruxelles, 1-4 Luglio 1997.
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